

# Evaluating the Performance of Dynamic Database Applications

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## 1 Introduction

In Database Management Systems (DBMSs), architectural or optimisation choices, efficiency comparison or tuning all require the assessment of system performance. Traditionally, this is achieved with the use of benchmarks, i.e., synthetic workload models (databases and operations) and sets of performance metrics. To the best of our knowledge, none of the existing database benchmarks incorporate the possibility of change in the access patterns, whereas in real life, almost no application always accesses the same data in the same order repeatedly. Furthermore, the ability to adapt to changes in access patterns is critical to database performance. Highly tuning a database to perform well for only one particular access pattern can lead to poor performance when different access patterns are used. In addition, the performance of a database on a particular trace provides little insight into the reasons behind its performance, and thus is of limited use to database researchers or engineers, who are interested in the identification and improvement in the performance of particular components of the system. Hence, this chapter aims to present a new perspective on DBMS performance evaluation by exploring how to assess the dynamic behavior of DBMSs.

More precisely, this chapter presents a benchmarking framework that allow users to explore the performance of databases under *different* styles of access pattern change. In contrast, benchmarks of the TPC family aim to provide *standardised* means of comparing systems for vendors and customers. In this chapter, we take a look at how dynamic application behavior can be modeled and propose the *Dynamic Evaluation Framework* (DEF). DEF contains a set of protocols which in turn define a set of styles of access pattern change. DEF by no means has exhausted all possible styles of access pattern change. However, it is designed to be fully extensible and its design allows new styles of change to be

easily incorporated. Finally, DEF is a generic platform that can be specialized to suit the particular needs of a given family of DBMS (e.g., relational, object, object-relational, or XML). In particular, it is designed to be implemented on top of an existing benchmark so that previous benchmarking research and standards can be reused.

In this chapter, we show the utility of DEF by creating an instance of DEF called the *Dynamic object Evaluation Framework* (DoEF) (He & Darmont, 2003). DoEF is designed for object databases. Note that, in the remainder of this chapter, we term Object Database Management Systems (ODBMSs) both object-oriented and object-relational systems, indifferently. ODBMSs include most multimedia and XML DBMSs, for example.

To illustrate the effectiveness of DoEF, this chapter presents the results of two sets of experiments. First it presents benchmark results of four state of the art dynamic clustering algorithms (Bullat & Schneider, 1996; Darmont, Fromantin, Regnier, Gruenwald, & Schneider, 2000; He, Marquez, & Blackburn, 2000). There are three reasons for choosing to test the effectiveness of DoEF using dynamic clustering algorithms: (1) ever since the “early days” of object database management systems, clustering has been proven to be one of the most effective performance enhancement techniques (Gerlhof, Kemper, & Moerkotte, 1996); (2) the performance of dynamic clustering algorithms is very sensitive to changing access patterns; and (3) despite this sensitivity, no previous attempt has been made to benchmark these algorithms in this way. Next, the utility of DoEF is further demonstrated by benchmarking two transactional object stores: Platypus (He, Blackburn, Kirby, & Zigman, 2000) and SHORE (Carey, DeWitt, Franklin, Hall, McAuliffe, Naughton, Schuh, Solomon, Tan, Tsatalos, White, & Zwilling, 1994).

The remainder of this chapter is organised as follows. Section 2 provides an overview of existing DBMS benchmarks. Sections 3 and 4 describe in detail the DEF framework and its object-oriented instance DoEF, respectively. Section 5 presents and discusses the experimental results we achieved with DoEF. We finally conclude this chapter in Section 6 and provide future research directions in Section 7.

## 2 State of the Art: Existing Database Benchmarks

We provide in this section an overview of the prevalent benchmarks that have been proposed in the literature for evaluating the performances of DBMSs. Note that, to the best of our knowledge, none of these benchmarks incorporate any dynamic application behavior.

In the world of relational databases, the Transaction Processing Performance Council (TPC), a non-profit institute founded in 1988, defines standard benchmarks, verifies their correct application, and publishes the results. The TPC benchmarks include TPC-C (TPC, 2005) for OLTP; and TPC-H (TPC, 2003a) and TPC-R (TPC, 2003b) for decision support. These last benchmarks were to be replaced by the TPC-DS data warehouse benchmark (Poess, Smith, Kollar, & Larson, 2002), but it is not completed yet and alternatives have appeared, such as the *Data Warehouse Engineering Benchmark* (Darmont, Bentayeb, & Boussaid, 2005). Finally, the TPC has also specified benchmarks for web commerce: TPC-W (TPC, 2002) and web services: TPC-App (TPC, 2004). All these benchmarks feature an elaborate database and set of operations, and except in DWEB, both are fixed. In the TPC benchmarks, the only parameter is indeed the database size (scale factor).

In contrast, there is no standard object-oriented database benchmark. However, the OO1 benchmark (Cattell, 1991), the HyperModel benchmark (Anderson, Berre, Mallison, Porter, & Schneider, 1990), and the OO7 benchmark (Carey, DeWitt, & Naughton, 1993) may be considered as *de facto* standards. They are all designed to mimic engineering applications such as CAD, CAM, or CASE applications. They range from OO1, that has a very simple schema (two classes) and only three simple operations, to OO7, that is more generic and provides both a much richer and more customisable schema (ten classes), and a wider range of operations (fifteen complex operations). However, even OO7's schema is static and still not generic enough to model other types of applications like financial, telecommunications and multimedia applications (Tiwary, Narasayya, & Levy, 1995). Furthermore, each step in adding complexity makes these benchmarks harder to implement. Finally, the *Object Clustering Benchmark* (OCB) has been proposed as a generic benchmark that is able to simulate the

behavior of other main object-oriented benchmarks (Darmont, Petit, & Schneider, 1998; Darmont & Schneider, 2000). OCB is further detailed in Section 4.1.

Object-relational benchmarks, such as the BUCKY benchmark (Carey, DeWitt, Naughton, Asgarian, Brown, Gehrke, & Shah, 1997) and the *Benchmark for Object-Relational Databases* (BORD) (Lee, Kim, & Kim, 2000), are query-oriented benchmarks that are specifically aimed at evaluating the performances of object-relational database systems. For instance, BUCKY only features operations that are specific to object-relational systems, since typical object navigation has already been tested by other benchmarks (see above). Hence, these benchmarks focus on queries involving object identifiers, inheritance, joins, class references, inter-object references, set-valued attributes, flattening queries, object methods, and various abstract data types. The database schema is also static in these benchmarks.

Carey and Franklin have also designed a set of workloads for measuring the performance of their client-server Object-Oriented Database Management Systems (OODBMSs) (Carey, Franklin, Livny, & Shekita, 1991; Franklin, Carey, & Livny, 1993). These workloads operate at the page grain instead of the object grain, i.e., synthetic transactions read or write pages instead of objects. The workloads contain the notion of hot and cold regions (some areas of database are more frequently accessed compared to others), attempting to approximate real application behaviour. However, the hot region never moves, meaning no attempt is made to model dynamic application behaviour.

Finally, a new family of benchmarks has recently appeared to specifically evaluate the performances of XML databases in various contexts: data-centric or document-centric XML databases, single or multi-document XML databases, global or micro benchmark, etc (Lu, Yu, Wang, Zheng, Jiang, Yu, & Zhou, 2005). These so-called XML benchmarks include XMach-1 (Böhme & Rahm, 2001), XOO7, an XML extension of OO7 (Bressan, Lee, Li, Lacroix, & Nambiar, 2002), the Michigan benchmark (Runapongsa, Patel, Jagadish, & Al-Khalifa, 2002), XMark (Schmidt, Waas, Kersten, Carey, Manolescu, & Busse, 2002), and XBench (Yao, Ozsu, & Khandelwal, 2004). However, none of them evaluate the dynamic behavior of XML database applications.

### 3 The Dynamic Evaluation Framework (DEF)

The primary goal of DEF is to evaluate the dynamic performance of DBMSs. To make the work of DEF more general, we have made two key decisions: define DEF as an extensible framework; and reuse existing and standard benchmarks when available.

#### 3.1 Dynamic Framework

We start by giving an example scenario that the framework can mimic. Suppose we are modeling an on-line book store in which certain groups of books are popular at certain times. For example, travel guides to Australia during the 2000 Olympics may have been very popular. However, once the Olympics is over, these books may suddenly or gradually become less popular.

Once the desired book has been selected, information relating to the book may be required. Example required information includes customer reviews of the book, excerpts from the book, picture of the cover, etc. If the data are stored in an ODBMS, retrieving the related information is translated into an object graph navigation with the traversal root being the selected book. After looking at the related information for the selected book, the user may choose to look at another book by the same author. When information relating to the newly selected book is requested, the newly selected book becomes the root of a new object graph traversal.

Next, we give an overview of the five main steps of the dynamic framework and in the process show how the above example scenario fits in.

1. **H-region parameters specification:** The dynamic framework divides the database into regions of homogeneous access probability (H-regions). In our example, each H-region represents a different group of books, each group having its own probability of access. In this step, we specify the characteristics of each H-region, e.g., its size, initial access probability, etc.
2. **Workload specification.** H-regions are responsible for assigning access probability to pieces of data (tuples or objects). However, H-regions do not dictate what to do then. We term the selected

tuple or object *workload root*. In the remainder of this chapter we will use the term “root” to mean workload root. In this step, we select the type of workload to execute after selecting the root.

3. **Regional protocol specification.** Regional protocols use H-regions to accomplish access pattern change. Different styles of access pattern change can be accomplished by changing the H-region parameter values with time. For example, a regional protocol may initially define one H-region with a high access probability, while the remaining H-regions are assigned low access probabilities. After a certain time interval, a different H-region may become the high access probability region. This, when translated to the book store example, is similar to Australian travel books becoming less popular after the 2000 Olympics end.
4. **Dependency protocol specification.** Dependency protocols allow us to specify a relationship between the currently selected root and the next root. In our example, this is reflected in the customer deciding to select a book which is by the same author as the previously selected book.
5. **Regional and dependency protocol integration specification.** In this step, regional and dependency protocols are integrated to model changes in dependency between successive roots. An example is a customer using our on-line book store, who selects a book of interest, and then is confronted with a list of *currently* popular books by the same author. The customer then selects one of the listed books (modeled by dependency protocol). The set of *currently* popular books by the same author may change with time (modeled by regional protocol).

The first three steps we have described are generic, i.e., they can be applied on any selected benchmark and system type (relational, object-oriented, or object-relational). The two last steps are similar when varying the system type, but are nonetheless different because access paths and methods are substantially different in a relational system (with tables, tuples, and joins) and an object-oriented system (with objects and references), for instance.

Next, we further detail the concept of H-region and the generic regional protocol specification.

## 3.2 H-regions

H-regions are created by partitioning the objects of the database into non-overlapping sets. All objects in the same H-region has the same access probability. Here we use the term *access probability* to mean the likelihood that an individual object of the H-region will be accessed at a given moment in time. The parameters that define an H-region are listed below.

- *HR\_SIZE*: The size of the H-region is specified as a fraction of the database size. *Constraint*: The sum size of all regions must equal 1.
- *INIT\_PROB\_W*: The initial probability *weight* that is assigned to the region. The actual probability is derived from the probability weight, by dividing the probability weight of the region by the sum probability weight of all regions.
- *LOWEST\_PROB\_W*: The lowest probability weight this region can go down to.
- *HIGHEST\_PROB\_W*: The highest probability weight this region can go up to.
- *PROB\_W\_INCR\_SIZE*: The amount by which the probability weight of this region increases or decreases when change is requested.
- *OBJECT\_ASSIGN\_METHOD*: This determines the way objects are assigned into this region. The options are *random* selection and by *class* selection. *Random* selection picks objects randomly from anywhere in the database. By *class* selection places attempts to assign objects of the same class into the same H-region, as much as possible. It first sorts objects by class ID and then picks the first  $N$  objects (in sorted order), where  $N$  is the number of objects allocated to the H-region.
- *INIT\_DIR*: The initial direction that the probability weight increment moves in.

The access probability of an H-region can never be below *LOWEST\_PROB\_W* or above *HIGHEST\_PROB\_W*.

## 3.3 Regional Protocols

Regional protocols simulate access pattern change by first initializing the parameters of every H-region, and then periodically changing the parameter values in certain predefined ways. This chapter



documents three styles of regional change: moving window of change, gradual moving window of change, and cycles of change. Although these three styles of change together provide a good spectrum of ways in which access pattern can change, they are by no means exhaustive. Other researchers or framework users are encouraged to create new regional protocols of their own.

**Moving Window of Change Protocol.** This regional protocol simulates sudden changes in access pattern. In our on-line book store, this is translated to books suddenly becoming popular due to some event, and once the event passes, the books become unpopular very fast. For instance, books that are recommended in a TV show may become very popular in the few days after the show, but may quickly become unpopular when the next set of books are introduced. This style of change is accomplished by moving a window through the database. The objects in the window have a much higher probability of being chosen as root when compared to the remainder of the database. This is done by breaking up the database into  $N$  H-regions of equal size. One H-region is first initialised to be the hot region (where heat is used to denote probability of reference), and then after  $H$  root selections, a different H-region becomes the hot region.  $H$  is a user-defined parameter that reflects the rate of access pattern change.

- The database is broken up into  $N$  regions of equal size.
- All H-regions have the same value for *HIGHEST\_PROB\_W*, *LOWEST\_PROB\_W* and *PROB\_W\_INCR\_SIZE*.
- Set the *INIT\_PROB\_W* of one of the H-regions to equal *HIGHEST\_PROB\_W* (the hot region) and the rest of the H-regions get their *INIT\_PROB\_W* assigned to *LOWEST\_PROB\_W*.
- Set *PROB\_W\_INCR\_SIZE* of every region to equal *HIGHEST\_PROB\_W* - *LOWEST\_PROB\_W*.
- The *INIT\_DIR* parameter of all the H-regions are set to move downwards. Initially, the window is placed at the hot region. After every  $H$  root selections, the window moves from one H-region to another. The H-region that the window is moving *from* has its direction set to *down*. The H-region that the window is moving *into* has its direction set to *up*. Then, probability weights of the H-regions are incremented or decremented depending on the current direction of movement.

**Gradual Moving Window of Change Protocol.** The way this protocol differs from the previous one is that the hot region cools down gradually instead of suddenly. The cold regions also heat up gradually as the window is moved onto them. In our book store example, this style of change may depict travel guides to Australia gradually becoming less popular after the Sydney 2000 Olympics. As a consequence, travel guides to other countries may gradually become more popular. Gradual changes of heat may be more common in the real world.

This protocol is specified in the same way as the previous protocol with two exceptions. First, *PROB\_W\_INCR\_SIZE* is now user-specified instead of being the difference between *HIGHEST\_PROB\_W* and *LOWEST\_PROB\_W*. The value of *PROB\_W\_INCR\_SIZE* determines how vigorously access pattern changes at every change iteration. We use the term *change iteration* to mean the changing of access probabilities of the H-regions after every *H* (defined in the previous section) root selections. The second exception is in the way the H-regions change direction. The H-region that the window moves *into* has its direction *toggled*. The direction of the H-region that the window is moving *from* is *unchanged*. This way, the previous H-region is able to continue cooling down gradually or heating up gradually. When the access probability of a cooling H-region reaches its *LOWEST\_PROB\_W* it stops cooling and similarly a heating up H-region stops heating up when it reaches its *HIGHEST\_PROB\_W*.

**Cycles of Change Protocol.** This style of change mimics something like a bank where customers in the morning tend to be of one type (e.g., social category), and in the afternoon of another type. This, when repeated, creates a cycle of change. Cycles of change can be simulated using the following steps. Members of a set are not ordered.

- Break up the database into three H-regions. The first two H-regions represent objects going through the cycle of change. The third H-region represents the remaining unchanged part of the database. The *HR\_SIZE* of the first two H-regions are equal to each other and user-specified. The *HR\_SIZE* of the third H-region is equal to the remaining fraction of the database.

- Set the *LOWEST\_PROB\_W* and *HIGHEST\_PROB\_W* parameters of the first two H-regions to values that reflect the two extremes of the cycle.
- Set the *PROB\_W\_INCR\_SIZE* of the first two H-regions to both equal *HIGHEST\_PROB\_W* - *LOWEST\_PROB\_W*. Set the *PROB\_W\_INCR\_SIZE* of the third H-region to equal zero.
- The *INIT\_PROB\_W* of the first H-region is set to *HIGHEST\_PROB\_W* and the second to *LOWEST\_PROB\_W*.
- Set the *INIT\_DIR* of the hot H-region to down and the *INIT\_DIR* of the cold H-region to up.
- Again, the *H* parameter is used to vary the rate of access pattern change.

## 4 The Dynamic Object Evaluation Framework (DoEF)

In this section, we describe DoEF, which is an instance of DEF. DoEF is built on top of the *Object Clustering Benchmark* (OCB) and uses both the database built from the rich schema of OCB and the operations offered by OCB. Since OCB's generic model can be implemented within an object-relational system and most of its operations are relevant for such a system, DoEF can also be used in the object-relational context.

Next, we present the OCB benchmark and then detail the steps in DEF that are specific to the object-oriented context, i.e., the specification of the dependency protocols and their integration with the regional protocols.

### 4.1 The Object Clustering Benchmark (OCB)

OCB is a generic, tunable benchmark aimed at evaluating the performances of OODBMSs. It was first oriented toward testing clustering strategies (Darmont et al., 1998) and was later extended to become fully generic (Darmont & Schneider, 2000). The flexibility and scalability of OCB is achieved through an extensive set of parameters. OCB is able to simulate the behavior of the *de facto* standards in object-oriented benchmarking, namely OO1 (Cattell, 1991), HyperModel (Anderson et al., 1990), and OO7 (Carey et al., 1993). Furthermore, OCB's generic model can be implemented within an object-

relational system easily and most of its operations are relevant for such a system. We only provide here an overview of OCB. Its complete specification is available in (Darmont & Schneider, 2000). The two main components of OCB are its database and workload.

**Database.** The OCB database is made up of  $NC$  classes derived from the same metaclass (Figure 1). Classes are defined by two parameters:  $MAXNREF$ , the maximum number of references in the instances and  $BASESIZE$ , an increment size used to compute the  $InstanceSize$ . Each  $CRef$  (class reference) has a type:  $TRef$ . There are  $NTREF$  different types of references (e.g., inheritance, aggregation...). Finally, an *Iterator* is maintained within each class to save references toward all its instances.

**Fig. 1.** OCB database schema

Each object possesses  $ATTRANGE$  integer attributes that may be read and updated by transactions. A *Filler* string of size  $InstanceSize$  is used to simulate the actual size of the object. After instantiating the schema, an object  $O$  of class  $C$  points through the  $ORef$  references to at most  $C.MAXNREF$  objects. There is also a backward reference (*BackRef*) from each referenced object toward the referring object  $O$ .

The database generation proceeds through three steps.

1. Instantiation of the *CLASS* metaclass into  $NC$  classes and selection of class level references. Class references are selected to belong to the  $[Class.ID - CLOCREF, Class.ID + CLOCREF]$  interval. This models locality of reference at the class level.
2. Database consistency check-up: suppression of all cycles and discrepancies within the graphs that do not allow them, e.g., inheritance graphs or composition hierarchies.

3. Instantiation of the *NC* classes into *NO* objects and random selection of the object references. Object references are selected to belong to the  $[OID - OLOCREF, OID + OLOCREF]$  interval. This models locality of reference at the instance level.

The main database parameters are summarized in Table 1.

Parameter name	Parameter	Default value
NC	Number of classes in the database	50
MAXNREF( <i>i</i> )	Maximum number of references, per class	10
BASESIZE( <i>i</i> )	Instances base size, per class	50 bytes
NO	Total number of objects	20,000
NREFT	Number of reference types	4
ATTRANGE	Number of integer attributes in an object	1
CLOCREF	Class locality of reference	NC
OLOCREF	Object locality of reference	NO

**Table 1.** OCB database main parameters

**Workload.** The operations of OCB are broken up into four categories.

- *Random Access:* Access to *NRND* randomly selected objects.
- *Sequential Scan:* Randomly select a class and then access all its instances. A *Range Lookup* additionally performs a test on the value of *NTEST* attributes, for each accessed instance.
- *Traversal:* There are two types of traversals in OCB. *Set-oriented accesses* (or associative accesses) perform a breadth-first search. *Navigational Accesses* are further divided into *Simple Traversals* (depth-first searches), *Hierarchy Traversals* that always follow the same reference type, and *Stochastic Traversals* that select the next link to cross at random. Each traversal proceeds from a randomly chosen root object, and up to a predefined depth. All the traversals can be reversed by following the backward links.
- *Update:* Update operations are also subdivided into different types. *Schema Evolutions* are random insertions and deletions of *Class* objects (one at a time). *Database Evolutions* are random

insertions and deletions of objects. *Attribute Updates* randomly select *NUPDT* objects to update, or randomly select a class and update all of its objects (*Sequential Update*).

In DoEF, the workload type is selected from these types. For *sequential scans*, the class of the root object is used to decide which objects are scanned; for *traversals*, the root object becomes the root of the traversal; and for *updates*, either the class of the root object or just the root object is used to decide which objects are updated (depending on the particular update workload selected).

## 4.2 Dependency Protocols

There are many scenarios in which a person executes a query and then decides to execute another query based on the results of the first query, thus establishing a dependency between the two queries. In this chapter, we have specified four dependency protocols: *random* selection protocol, *by reference* selection protocol, *traversed objects* selection protocol, and *same class* selection protocol. Again, these protocols are not meant to be exhaustive and other researchers or benchmark users are encouraged to extend DoEF beyond these dependency protocols.

**Random Selection Protocol.** This method simply uses some random function to select the current root. This protocol mimics a person starting a completely new query after finishing the previous one.

$$r_i = RAND1()$$

$r_i$  is the ID of the  $i^{th}$  root object. The function  $RAND1()$  can be any random function. An example of  $RAND1()$  is a skewed random function that selects a certain group of root objects with a higher probability than others.

**By Reference Selection Protocol.** The current root is chosen to be an object referenced by the previous root. An example of this protocol in our on-line book store scenario is a person having finished with a selected book, who then decides to look at the next book in the series (assuming the books of the same series are linked together by structural references).

$$r_{i+1} = RAND2(RefSet(r_i, D))$$

$RefSet(r_i, D)$  is a function that returns the set of objects that the  $i^{th}$  root references.  $RAND2()$ , like  $RAND1()$  can be any random function. Two types of references can be used: structure references (S-references) and D-references. Structure references are simply the references obtained from the object graph. D-references are a new type of reference used for the sole purpose of establishing dependencies between roots of traversals. The parameter  $D$  is used to specify the number of D-references per object. Note if structure references are specified, then parameter  $D$  is not used.

**Traversed Objects Selection Protocol.** The current root is selected from the set of objects that are referenced in the previous traversal. An example is a customer in the first query requesting a list of books along with their authors and publishers (thus requiring the book objects themselves to be retrieved), who then decides to read an excerpt from one of the books listed.

$$r_{i+1} = RAND3(TraversedSet(r_i, C))$$

$TraversedSet(r_i, C)$  returns the set of objects referenced during the traversal that began with the  $i^{th}$  root.  $RAND3()$ , like  $RAND1()$  can be any random function. The parameter  $C$  is used to restrict the number of objects returned by  $TraversedSet(r_i, C)$ .  $C$  is specified as a fraction of the objects traversed. This way, the degree of locality of objects returned by  $TraversedSet(r_i, C)$  can be controlled (smaller  $C$  means higher degree of locality).

**Same Class Selection Protocol.** In same class selection, the currently selected root must belong to the same class as the previous root. Root selection is further restricted to a subset of objects of the class. The subset is chosen by a function that takes the previous root as a parameter. That is, the subset chosen is dependent on the previous root object. An example of this protocol is a customer deciding to select a book from our on-line book store which is by the same author as the previous selected book. In this case, the same class selection function returns books by the same author as the selected book.

$$r_{i+1} = RAND4(f(r_i, Class(r_i), U))$$

$Class(r_i)$  returns the class of the  $i^{th}$  root.  $RAND4()$ , like  $RAND1()$  can be any random function. The parameter  $U$  is user-defined and specifies the size of the set returned by function  $f()$ .  $U$  is specified as a fraction of the total class size.  $U$  can be used to increase or decrease the degree of locality between the objects returned by  $f()$ .  $f()$  always returns the same set of objects given the same set of parameters.

**Hybrid Setting.** The hybrid setting allows an experiment to use a mixture of the dependency protocols outlined above. Its use is important since it simulates a user starting a fresh random query after having followed a few dependencies. Thus, the hybrid setting is implemented in two phases. The first *randomisation phase* uses the random selection protocol to randomly select a root. In the second *dependency phase*, one of the dependency protocols outlined in the previous section is used to select the next root.  $R$  iterations of the second phase are repeated before going back to the first phase. The two phases are repeated continuously.

The probability of selecting a particular dependency protocol during the *dependency phase* is specified via the following settings:  $RANDOM\_DEP\_PROB$  (random selection),  $SREF\_DEP\_PROB$  (by reference selection using structure references),  $DREF\_DEP\_PROB$  (by reference selection using D-references),  $TRAVERSED\_DEP\_PROB$  (traversed objects selection), and  $CLASS\_DEP\_PROB$  (same class selection).

### 4.3 Integration of Regional and Dependency Protocols

Dependency protocols model user behavior. Since user behavior can change with time, dependency protocols should also be able to change with time. The integration of regional and dependency protocols allows us to simulate changes in the dependency between successive root selections. This is easily accomplished by exploiting the dependency protocols' property of returning a candidate set of objects when given a particular previous root. Up to now, the next root is selected from the candidate set by the use of a random function. Instead of using the random function, we partition the candidate set using H-regions and then apply regional protocols on these H-regions. When integrating with the



traversed objects dependency protocol, the following property must hold: whenever given the same root object, the same set of objects is always traversed. This way, the same previous root will return the same candidate set.

## 5 Tests and Results

This section details two sets of experiments we have conducted to evaluate the effectiveness of DoEF. In the first set of experiments four state of the art dynamic clustering algorithms are benchmarked. In the second set two real object stores are benchmarked.

For dynamic clustering algorithms we have conducted two sets of experiments: moving and gradual moving window of change regional protocol experiments; and moving and gradual moving S-reference protocol experiments. For the real object stores, we also conducted two sets of experiments: moving window of change protocol experiments; and moving window of change traversed objects experiment. There are two reasons for choosing these set of protocols to test: the space constraints prohibit us from showing results obtained using all combinations of protocols; and after testing many of the possible combinations we found for the particular clustering algorithms and real OODBs we have tested, the experiments presented gives the greatest insight into the effectiveness of DoEF.

### 5.1 Tested Systems and Algorithms

In this section, we briefly describe the dynamic clustering algorithms and object stores we have used in our experiments.

**Dynamic Clustering Algorithms.** Dynamic clustering is the periodic on-line re-organisation of objects in an ODBMS. The aim is to allow the physical placement of objects on disk to more closely reflect the pervading pattern of database access. Objects that are likely to be accessed together in the near future are placed in the same page, thereby reducing the number of disk I/Os.

Dynamic, Statistical and Tunable Clustering (DSTC) (Bullat & Schneider, 1996) is a dynamic clustering algorithm that has the feature of achieving dynamicity without adding high statistics collection

overhead and excessive volume of statistics. However, it does not take care to reduce I/O generated from the clustering process itself. The clustering algorithm is not very selective when deciding which pages to re-cluster. The effect is a page is re-clustered even if there is a slight benefit in re-clustering it. However, the slight benefit gained from re-clustering is often outweighed by the cost of loading the page into memory for re-clustering. This situation (re-clustering of slightly badly clustered pages) will become more frequent as access pattern changes more rapidly. It is for this reason we expect that DSTC will perform poorly when access pattern changes rapidly.

Detection & Reclustering of Objects (DRO) (Darmont et al., 2000) capitalizes on the experiences of DSTC and StatClust (Gay & Gruenwald, 1997) to produce less clustering I/O overhead and use less statistics. DRO uses various thresholds to limit the pages involved in re-clustering to only the pages that are most in need of re-clustering. We term this flexible conservative re-clustering. Experiments conducted using OCB show that DRO outperforms DSTC (Darmont et al., 2000). The improvement in performance is mainly attributed to the low clustering I/O overhead of DRO. In order to limit statistics collection overhead, DRO only uses *object frequency* and *page usage rate* information. In contrast, DSTC stores *object transition* information, which is much more costly. Since DRO chooses only a limited number of the worst clustered pages to re-cluster (flexible conservative re-clustering) it should perform better than DSTC when access pattern changes rapidly. This is because when access pattern changes rapidly, the benefits in re-clustering pages become lower and thus there will be more pages which only benefit slightly from re-clustering. DRO does not re-cluster these pages whereas DSTC does. This leads DSTC to generate larger clustering overhead for very slight improvements in clustering quality.

Opportunistic Prioritised Clustering Framework (OPCF) (He et al., 2000) is a framework for translating any static clustering algorithm (where re-clustering occurs off-line) into a dynamic clustering algorithm. OPCF creates algorithms that have the following key properties: read and write I/O opportunism and prioritisation of re-clustering. Read and write I/O opportunism refers to limiting re-clustering to pages that are currently in memory (in the case of read opportunism) and dirty (in

the case of write opportunism). This approach reduces the I/O overhead associated with re-clustering. Prioritisation of re-clustering refers to choosing a limited number of the worst clustered pages to be re-clustered first. This also reduces clustering overhead by reducing the number of pages re-clustered. Therefore OPCF clustering algorithms also perform flexible conservative re-clustering. Two dynamic clustering algorithms produced from the OPCF framework are presented in (He et al., 2000): dynamic graph partitioning algorithm (GP) and dynamic probability ranking principle algorithm (PRP). Since OPCF, like DRO, performs flexible conservative re-clustering, it should also perform well when access pattern changes very rapidly. We will use the term *flexible clustering algorithms* to refer to DRO and the OPCF dynamic clustering algorithms.

**Object stores.** Platypus (He et al., 2000) is a flexible high performance transactional object store, designed to be used as the storage manager for persistent programming languages. The design includes support for SMP concurrency: stand-alone, client-server and client-peer distribution configurations; configurable logging and recovery; and object management that can accommodate garbage collection and clustering mechanisms. In addition to these features, Platypus is built for speed. It features a new recovery algorithm derived from the popular ARIES (Mohan, Haderle, Lindsay, Pirahesh, & Schwarz, 1992) recovery algorithm, which removes the need for log sequence numbers to be present in store pages; a zero-copy memory-mapped buffer manager with controlled write-back behaviour; and a novel fast and scalable data structure (splay trees) used extensively for accessing metadata.

SHORE (Carey et al., 1994) is a transactional persistent object system that is designed to serve the needs of a wide variety of target applications, including persistent programming languages. It has a peer-to-peer distribution configuration. Like Platypus, it also has a focus on performance.

## 5.2 Dynamic Clustering Experiments

These experiments use DoEF to compare the performance of four state of the art dynamic clustering algorithms: DSTC, DRO, OPCF-PRP, and OPCF-GP (see Section 5.1). The parameters we have used for the dynamic clustering algorithms are shown in Table 2. In the interests of space, we do not include

their description in this chapter. However, they are wholly described in their respective papers. The clustering techniques have been parameterized for the same behaviour and best performance.

Parameter	Value	Parameter	Value		
$n$	200	MinUR	0.001		
$n_p$	1	MinLT	2		
$p$	1000	PCRate	0.02		
$T_{fa}$	1.0	MaxD	1		
$T_{fe}$	1.0	MaxDR	0.2		
$T_{fc}$	1.0	MaxRR	0.95		
$w$	0.3	SUInd	true		

  

Parameter	PRP value	GP value
N	200	200
CBT	0.1	0.1
NPA	50	50
NRI	25	25

(a) DSTC

(b) DRO

(c) OPCF

**Table 2.** DSTC, DRO, OPCF-PRP, and OPCF-GP parameters

The experiments are conducted on the Virtual Object-Oriented Database simulator (VOODB) (Darmont & Schneider, 1999). VOOB is based on a generic discrete-event simulation framework. Its purpose is to allow performance evaluations of OODBMSs in general, and optimisation methods like clustering in particular. VOOB has been validated for two real-world OODBMSs, O<sub>2</sub> (Deux, 1991) and Texas (Singhal, Kakkad, & Wilson, 1992). The VOOB parameter values we have used are depicted in Table 3 (a). Simulation is chosen for this experiment for two reasons. First, it allows rapid development and testing of a large number of dynamic clustering algorithms (all previous dynamic clustering papers compared at most two algorithms). Second, it is relatively easy to simulate accurately, read, write and clustering I/O (the dominating metrics that determine the performance of dynamic clustering algorithms).

Since DoEF uses the OCB database and operations, it is important for us to document the OCB settings we have used for these experiments. The values of the database parameters we have used are shown in Table 3 (b). The sizes of the objects we have used varies from 50 to 1600 bytes, with the average size being 233 bytes. A total of 100,000 objects are generated for a total database size of 23.3 MB. Although this is a small database size, we have also used a small buffer size (4 MB) to

keep the database to buffer size ratio large. Clustering algorithm performance is indeed more sensitive to database to buffer size ratio than database size alone. The operation we have used for all the experiments is the simple, depth-first traversal with traversal depth 2. The simple traversal is chosen since it is the only traversal that always accesses the same set of objects given a particular root. This establishes a direct relationship between varying root selection and changes in access pattern. Each experiment involved executing 10,000 transactions.

The main DoEF parameter settings we have used in this study are shown in Table 4. These DoEF settings are common to all experiments in this chapter. The *HR\_SIZE* setting of 0.003 (remember this is the database population from which the traversal *root* is selected) creates a hot region about 3% the size of the database (each traversal touches approximately 10 objects). This fact is verified from statistical analysis of the trace generated. The *HIGHEST\_PROB\_W* setting of 0.8 and *LOWEST\_PROB\_W* setting of 0.0006, produces a hot region with 80% probability of reference and the remaining cold regions with a combined reference probability of 20%. These settings are chosen to represent typical database application behaviour. Gray cites statistics from a real videotext application in which 3% of the records got 80% of the references (Gray & Putzolu, 1987). Carey uses a hot region size of 4% with a 80% probability of being referenced in the HOTCOLD workload we have used to measure data caching tradeoffs in client-server OODBMSs (Carey et al., 1991). Franklin uses a hot region size of 2% with a 80% probability of being referenced in the HOTCOLD workload we have used to measure the effects of local disk caching for client server OODBMSs (Franklin et al., 1993). In addition to the results reported in this chapter, we also tested the sensitivity of the results to variations in hot region size and probability of reference. We found the algorithms show similar general tendencies at different hot region sizes and probability of reference. It is for this reason and in the interests of space we omit these results.

The dynamic clustering algorithms shown on the graphs in this section are labeled as follows:

Parameter description	Value
System class	Centralized
Disk page size	4096 bytes
Buffer size	4 MB
Buffer replacement policy	LRU-1
Pre-fetching policy	None
Multiprogramming level	1
Number of users	1
Object initial placement	Sequential

(a) VOODB parameters

Parameter description	Value
Number of classes in the database	50
Maximum number of references, per class	10
Instances base size, per class	50
Total number of objects	100000
Number of reference types	4
Reference types random distribution	Uniform
Class reference random distribution	Uniform
Objects in classes random distribution	Uniform
Objects references random distribution	Uniform

(b) OCB parameters

**Table 3.** VOODB and OCB parameters

Parameter name	Value
<i>HR_SIZE</i>	0.003
<i>HIGHEST_PROB_W</i>	0.80
<i>LOWEST_PROB_W</i>	0.0006
<i>PROB_W_INCR_SIZE</i>	0.02
<i>OBJECT_ASSIGN_METHOD</i>	Random object assignment

**Table 4.** DoEF parameters

- **NC**: No Clustering;
- **DSTC**: Dynamic Statistical Tunable Clustering;
- **GP**: OPCF (greedy graph partitioning);
- **PRP**: OPCF (probability ranking principle);
- **DRO**: Detection & Reclustering of Objects.

As we discuss the results of these experiments, we focus our discussion on the relative ability of each algorithm to adapt to changes in access pattern, i.e., as rate of access pattern change increases, we seek to know which algorithm exhibits more rapid performance deterioration. This contrasts from discussing which algorithm gives the best absolute performance. All the results presented here are in terms of total I/O. Total I/O is the sum of transaction read I/O, clustering read and clustering write I/O. Thus, the results give an overall indication of the performance of each clustering algorithm, including each algorithm’s clustering I/O overhead.

**A priori Analysis.** In this section we analyse the relative performances of the dynamic clustering algorithms based on the characteristics of DSTC, DRO, OPCF-PRP, and OPCF-GP. For the moving window of change protocol experiments we expect the relative difference in performance between DSTC and the flexible clustering algorithms to increase with increasing rate of change. This is because DSTC does not do flexible conservative re-clustering and thus incurs high re-clustering overheads. The relative difference between the different flexible clustering algorithms should not change by much with increasing rate of change since they all limit the clustering overheads to a bounded amount. In terms of the shapes of the curves, we expect DSTC to perform linearly worse with increasing rate of change. This is because it does not bound the clustering overhead. In contrast the flexible dynamic clustering algorithms’ performance will increase with increasing rate of change but flat after a certain point (we call this the saturation point). This is because these algorithms bound the clustering overhead and thus there is a bound on how its performance.

In terms of the gradual moving window of change experiments, we expect the relative differences between the algorithms to stay similar as the rate of change increases. The reason is this change

protocol is very mild and therefore do not cause the flexible clustering algorithms to reach their saturation point. In terms of the shapes of the curves, we expect the performance of all the algorithms to perform close to linear with increasing rate of change of access pattern. This is because increases in the rate of change of access pattern causes the benefit of re-clustering to diminish, this increase is constant and does not reach a saturation point due to the mild style of change.

**Moving and Gradual Moving Regional Experiments.** In these experiments, we have used the regional protocols *moving window of change* and *gradual moving window of change* to test each of the dynamic clustering algorithms' ability to adapt to changes in access pattern. The regional protocol settings we have used are shown in Table 4. We vary the parameter  $H$ , rate of access pattern change.

The results for these experiments are shown in Figure 2. There are three main results from this experiment. Firstly, when rate of access pattern change is small (when parameter  $H$  is less than 0.0006 in Figure 2 (a) and all of Figure 2 (b)), all algorithms show similar performance trends (rate of performance degradation). This implies at moderate levels of access pattern change all algorithms are approximately equal in their ability to adapt to the change. Secondly, when the more vigorous style of change is applied (Figure 2 (a)), all dynamic clustering algorithms' performance quickly degrades to worse than no clustering. Thirdly, when access pattern change is very vigorous (when parameter  $H$  is greater than 0.0006 in Figure 2 (a)), DRO and OPCF algorithms GP and PRP show a better trend performance (rate of performance degradation), implying DRO and OPCF are more robust to access pattern change. This supports our analysis in Section 5.2.

**Moving and Gradual Moving S-Reference Experiments.** In these experiments, we explore the effect that changing pattern of access has on the *S-reference dependency protocol*. This is accomplished by using the integrated regional dependency protocol method outlined in Section 4.3. We integrated *S-reference dependency* with the *moving* and *gradual moving window of change* regional protocols. For this experiment, we use the hybrid dependency setting detailed in Section 4.2.  $R$  is set to 1. The first phase (random phase) of the hybrid setting requires a random dependency function. The random



(a) Moving Window of Change

(b) Gradual Moving Window of Change

**Fig. 2.** Regional dependency results. The x-axis is in  $\log_2$  scale.

function we use partitions the database into one hot and one cold region. The hot region is set to be 3% of the database size and has an 80% probability of reference (typical database application behaviour (Gray & Putzolu, 1987; Carey et al., 1991; Franklin et al., 1993)). S-reference dependency is the only dependency protocol used. The regional protocol settings are as described in Table 4.

The results for these experiments are shown in Figure 3. In the moving window of change results (Figure 3 (a)), DRO and the OPCF algorithms (GP and PRP) are again more robust to changes in access pattern than DSTC for moving window of change. However, in contrast to the previous experiment, DRO and OPCF algorithms never perform worse than NC by much, even when parameter  $H$  is 1 (access pattern changes after every transaction). The reason is that the cooling and heating of S-references is a milder form of access pattern change than the pure moving window of change regional protocol of the previous experiment. In the gradual moving window of change results shown in figure 3 (b), all dynamic clustering algorithms show approximately the same trend performance. This is similar to the observation made in the previous experiment. The analysis in Section 5.2 support these observations.

(a) Moving Window of Change

(b) Gradual Moving Window of Change

**Fig. 3.** S-reference dependency results. The x-axis is in  $\log_2$  scale.

### 5.3 Object Store Experiments

In this section, we report the results of using DoEF to compare the performance of two real object stores: SHORE and Platypus.

SHORE has a layered architecture that allows users to choose the level of support appropriate for a particular application. The lowest layer of SHORE is the SHORE Storage Manager (SSM), which provides basic object reading and writing primitives. Using the SHORE SSM, we have constructed PSI-SSM, a thin layer providing PSI (Blackburn, 1998) compliance for SSM. By using the PSI interface, the same DoEF code could be used for both Platypus and SHORE. The buffer replacement policy that SHORE uses is CLOCK. We use SHORE version 2.0 for all of the experiments reported in this chapter.

The Platypus implementation we have used for this set of experiments has the following features: physical object IDs; the NOFORCE/STEAL recovery policy (Franklin, 1997); zero-copy memory mapped buffer cache; the use of hash-splay trees to manage metadata; PSI compliance; the system is SMP re-entrant and supports multiple concurrent client threads per process as well as multiple concurrent client processes. Limitations of the Platypus implementation at the time of writing include:

the failure-recovery process is untested (although logging *is* fully implemented); virtual address space reserved for metadata is not recycled; the store lacks a sophisticated object manager with support for garbage collection and dynamic clustering, and lacks support for distributed store configurations. Platypus uses the LRU replacement policy.

In this sets of experiments, the SHORE and Platypus implementations do not include dynamic clustering algorithms. In contrast to the previous experiment, we are interested here in comparing the other factors (besides clustering) that affect system performance. The experiments in this section are conducted using Solaris 7 on an Intel machine with dual Celeron 433Mhz processors, 512 MB of memory and a 4 GB hard disk. The OCB database and workload settings we have used for this experiment are the same as for the previous set of experiments — see Section 5.2, with the exception that a total of 400,000 objects is generated instead of 100,000. The reason for using a larger database size is that the real object stores are configured with a larger buffer cache, therefore we need to increase the database size in order to test the swapping. The size of the objects we have used vary from 50 to 1200 bytes, with the average size being 269 bytes. Therefore, the total database size is 108 MB.

**A priori Analysis.** For the moving window of change protocol experiments we expect the performance of Platypus to start well in front of SHORE but its lead should rapidly diminishes as the rate of access pattern change increases. The reason lies in the change in access locality when the rate of access pattern change. When the rate of access pattern change is low, access locality is high (due to small and slow moving hot region), and thus most object requests can be satisfied from the buffer cache. However as the rate of access pattern change increases, access locality diminishes which results in more buffer cache misses. Thus, the reason behind Platypus' poor performance lies in its poor swapping performance. Platypus's poor swapping performance is due to the low degree of concurrency (coarse grained locking) between the page server and the client process when swapping is in progress (a deficiency in the implementation).

In the traversed objects protocol experiments we expect the results to again show the performance of Platypus diminishes at a faster rate than SHORE. The reason for this behaviour can again be

explained by Platypus' poor swapping performance. However, the saturation is expected to occur later point than for the moving window of change protocol since the degree of locality in this protocol is higher.

**Moving Window of Change Regional Experiment.** In this experiment, we use the *moving window of change* protocol to compare the effects that changing pattern of access has on Platypus and SHORE. The regional protocol settings we have used are the same as shown in Table 4. The buffer size is set to 61 MB. Note that both Platypus and SHORE have their own buffer managers with user-defined buffer sizes.

The results for this experiment are shown in Figure 4. The results show the trend predicted in Section 5.3, namely the performance of Platypus start well in front of SHORE but its lead rapidly diminishes as the rate of access pattern change increases.

**Fig. 4.** Moving window of change regional protocol results. The x-axis is in  $\log_2$  scale.

**Moving Window of Change Traversed Objects Experiment.** In this experiment, we compare the performance of Platypus and SHORE in the context of moving *traversed objects dependency protocol*. This is accomplished by using the integrated regional dependency protocol method outlined in Section 4.3. We have integrated *traversed objects dependency* protocol with the *moving window*

regional protocol. For this experiment, we use the hybrid dependency setting detailed in Section 4.2.  $R$  is set to 1. The random function we use partitions the database into one hot and one cold region. The hot region is set to be 0.01 fraction of the database size, and the cold region is assigned the remaining portion of the database. 99% of the roots are selected from the hot region. The  $C$  parameter is set to 1.0. Traversed objects dependency is the only dependency protocol we have used. The regional protocol parameters we have used are identical to those used in the previous experiment, with the exception  $HR\_SIZE$  is set to 0.05. In this experiment, the buffer size we have used is only 20 MB as opposed to 61 MB in the previous experiment, because this experiment has a smaller working set size, thus, at 61 MB, swapping would not occur (even when  $H$  is one). The reason behind the small working set size lies in the fact that the random function we have used does not move its hot region.

The results for this experiment are shown in Figure 5. It's behavior is consistent with that described in Section 5.3.

**Fig. 5.** Traversed objects results. The x-axis is in  $\log_2$  scale. The minimum and maximum coefficients of variation are 0.005 and 0.037, respectively.

## 6 Conclusion

In this chapter, we have conducted a short survey of existing benchmarking techniques. We have identified that no existing benchmark evaluate the dynamic performance of database applications. We then presented in detail the specification of a generic framework for database benchmarking, DEF, which allows DBMSs' designers and users to test the performances of a given system in a dynamic setting. We have also instantiated DEF in an object-oriented context under the name of DoEF, to illustrate how such specialization can be performed.

DEF is designed to be readily extensible along two axes. First, since this is, to the best of our knowledge, the first attempt at studying the dynamic behavior of DBMSs, we have taken great care to make the incorporation of new styles of access pattern change as painless as possible, mainly through the definition of H-regions. We actually view the DEF software as an open platform that is available to other researchers for testing their own ideas. The DoEF code we have used in both our object clustering simulation experiments and our implementation for Platypus and SHORE is freely available for download.

Second, although we have considered an object-oriented environment in this study with DoEF, we can also apply the concepts developed in this chapter to other types of databases. Instantiating DEF for object-relational databases, for instance, should be relatively easy. Since OCB can be quite easily adapted to the object-relational context (even if extensions would be required, such as abstract data types or nested tables, for instance), DEF can be used in the object-relational context too.

The main objective of DEF is to allow researchers and engineers to explore the performance of databases (identify components that are causing poor performance) within the context of changing patterns of data access. Our experimental results involving dynamic clustering algorithms and real object stores have indeed demonstrated DoEF's ability to meet this objective. Within the dynamic clustering context, two new insights are gained: (1) dynamic clustering algorithms can deal with moderate levels of access pattern change but performance rapidly degrades to be worse than no clustering when vigorous styles of access pattern change are applied; and (2) flexible conservative

re-clustering is the key in determining a clustering algorithm's ability to adapt to changes in access pattern. In the performance comparison between the real object stores Platypus and SHORE, the use of DoEF allowed us to identify Platypus' poor swapping performance.

## **7 Future Trends**

In the past, most research has focused on the static optimization of database systems. As a result, this is now a very mature area. The next frontier in database optimization is to optimize queries while taking query patterns into consideration. This leads to the need to evaluate such systems in a quantitative manner. This study takes the first step in developing a benchmark for this purpose.

An interesting direction for future work is to use DEF to keep on acquiring knowledge about the dynamic behavior of various commercial and research DBMSs. This knowledge could of course be used to improve the performance of these systems. Furthermore, comparing the dynamic behavior of different systems, though an interesting task in itself, may inspire us to develop new styles of access pattern change. New styles of access pattern change identified in this and other ways may be incorporated into DEF.

Finally, the effectiveness of DEF at evaluating other aspects of database performance could also be explored. Data clustering is indeed an important performance optimisation technique, but other strategies such as buffer replacement and prefetching should also be evaluated.

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