GRID-BASED CLUSTERING OF WAZE DATA ON A RELATIONAL DATABASE

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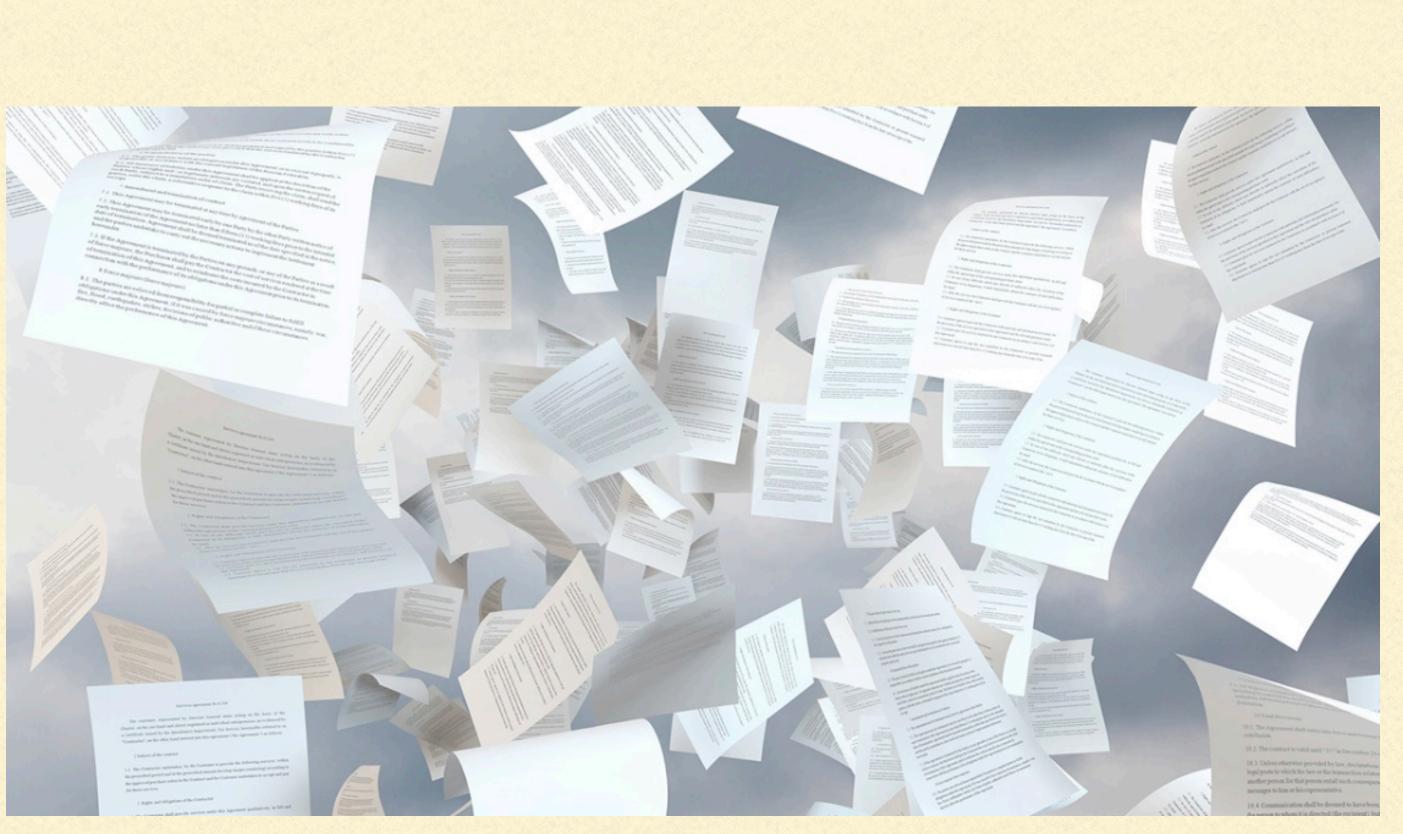
Mobility data -> City planing

Mobility knowledge -> Decision making



Big data flow -> Events continuously produced

Increasing dataset





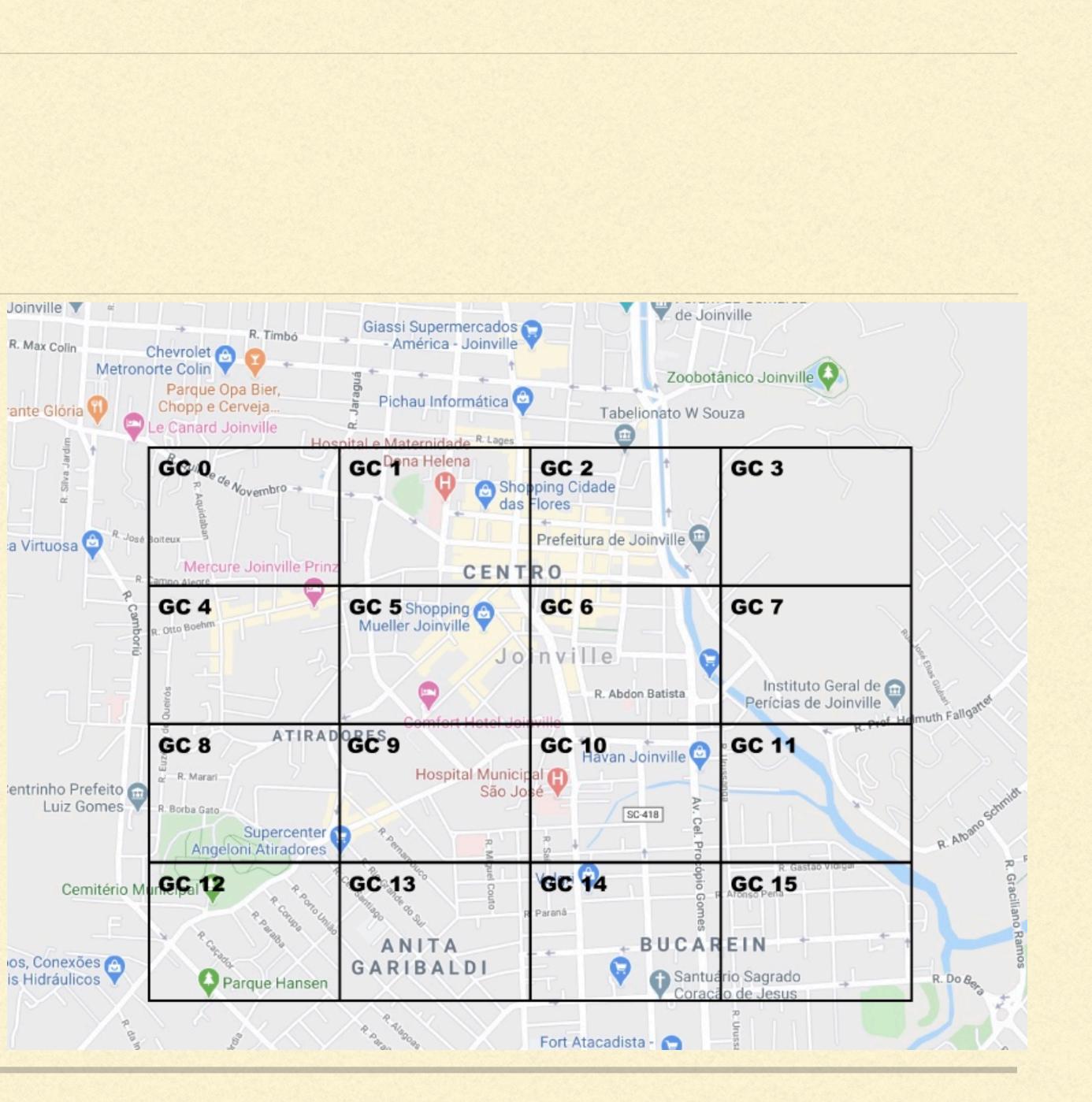
- Speed data is reported -> Stored as individual records
- Low insertion cost
- Processing spatial-temporal queries
- Avoid exhaustive search -> Index structures



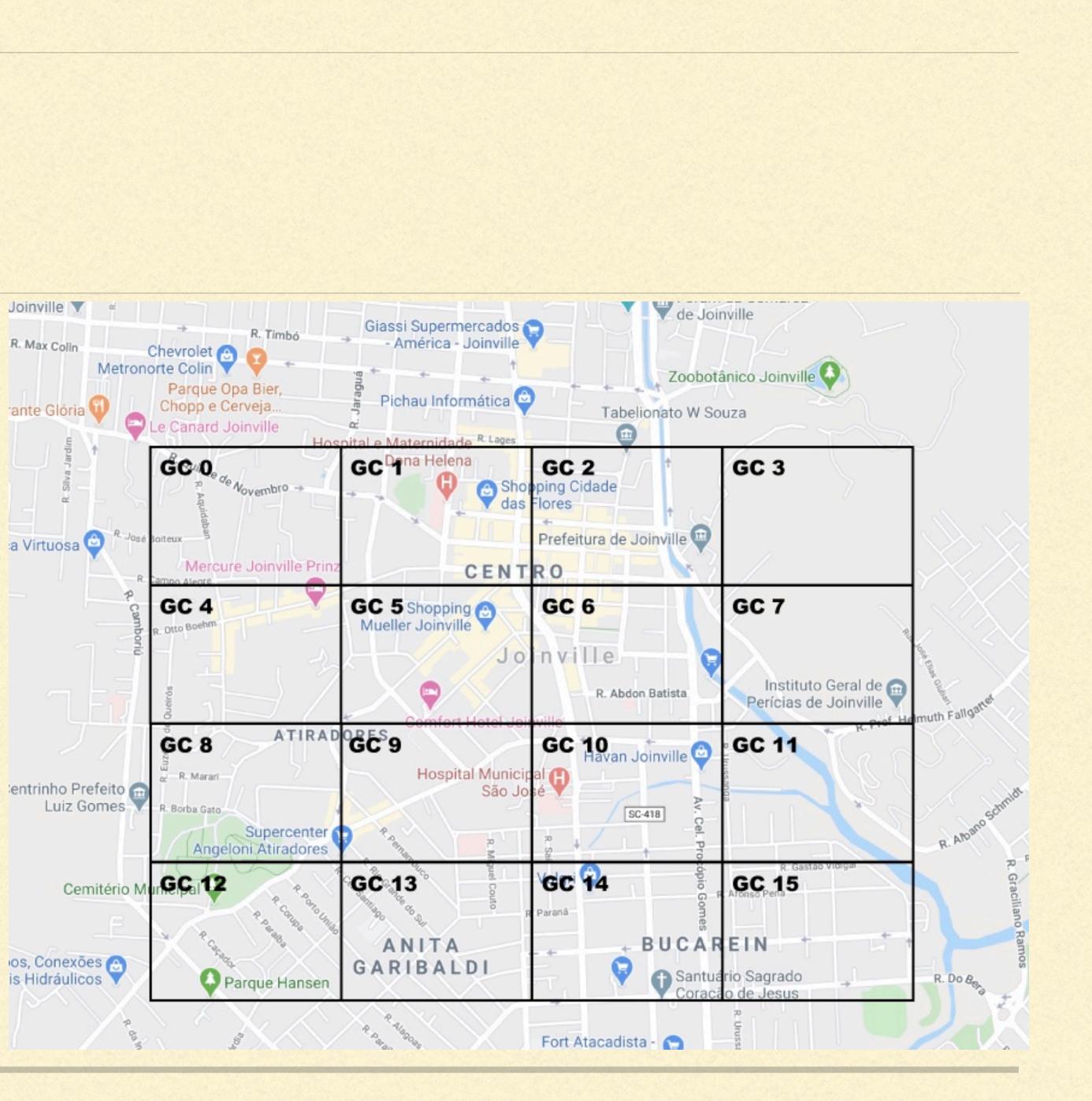
- Traditional structures adopted for spatial indexing
 - R-Trees (PostgresSQL, SQLite)
 - KD-Trees (Oracle, ExtremeDB)

Partitioning of a geographic

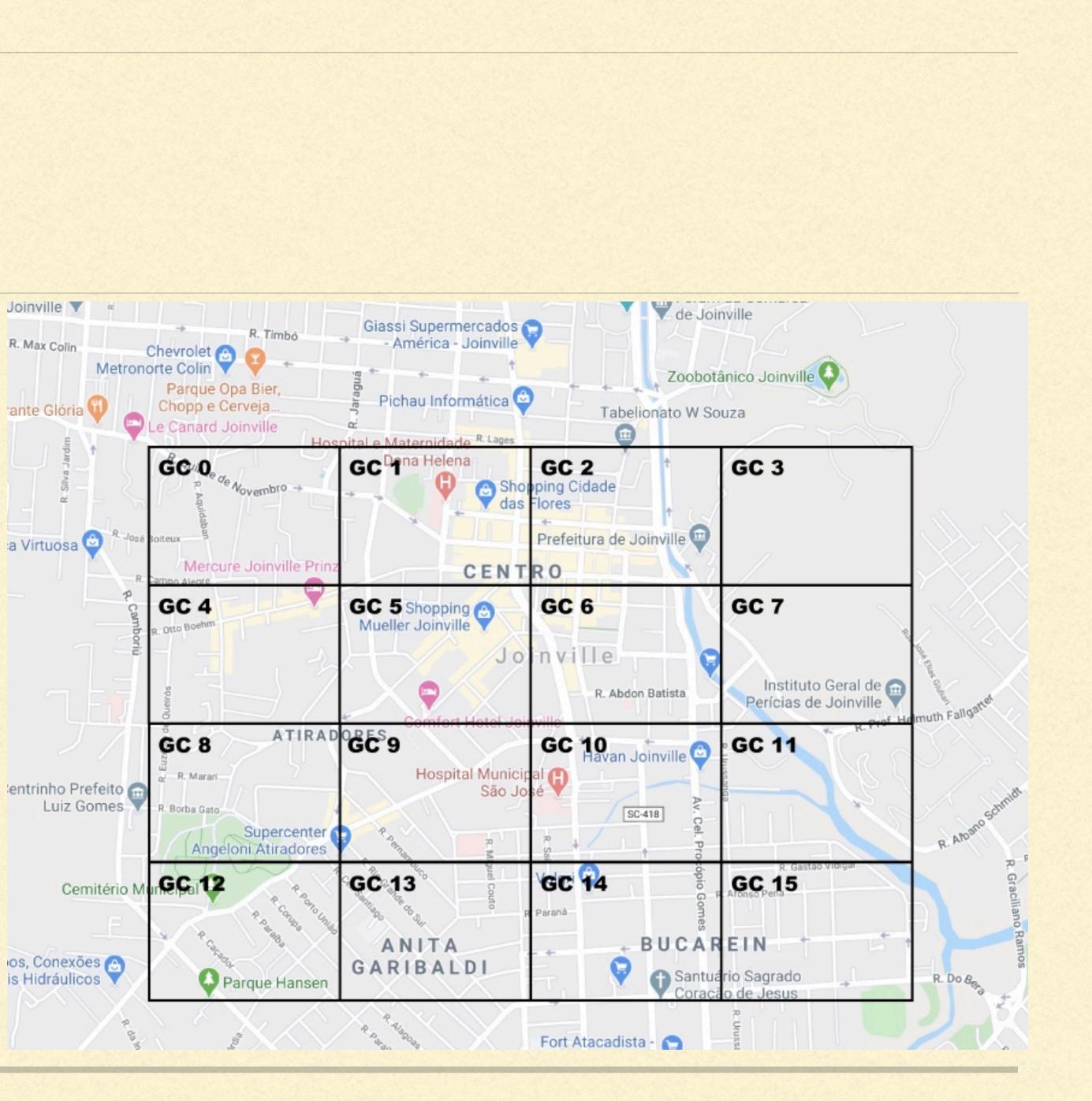
- Creating a grid composed of juxtaposed Geographic Cells (GC)
- Eliminate the possibility of data belonging to more than one GC



- Not a new idea
- Basis for index structures
 - Spatial R-Tree
 - GE-Tree



- Off-the-shelf relational database
- Traditional R-tree indexing
- Interest for developers
 - Spatial data
 - Using an existing database management system (DBMS)

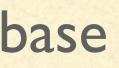


- Study case -> Data collected by Waze
 - Produced over a period of one year at Joinville, Brazil
 - Approached denoted Waze-GC

- Grid-based partitioning of data (Spatial R-Tree, GE-Tree, Geospark) Delimited geographic area -> Matrix and predetermined number of GCs Spatial R-Tree -> Moving objects R-tree with a grid on the leaves
 - Minimize the overlapping among minimum bounding rectangles (MBR)

- **GE-Tree**
 - Constant time to obtain the set of objects within GC
 - Nodes that split on demand
- GeoSpark -> Grid for a different purpose.
 - In-memory cluster -> Processing large-scale spatial data in Apache Spark
 - Grid -> Partition the data and assign cells to machines for parallel execution

- Work differs on the use of the grid
- Clustering data stored in a relational database
- Waze-GC does not consider
 - New indexing structures
 - Parallel processing of queries
- Waze-GC can be implemented on any relational database (RDB)



Mobility data management

- STIG tree
- TQ index

Both propose special structures for indexing mobility data

Not based on a grid

- STIG tree -> Processed in parallel on GPUs
 - KD-tree
 - Sets of events on the leaves
- TQ index -> Predict traffic jams
 - Location index and Time index
 - Both based on hash tables



- Waze-GC works with the same type of data
- Objective: determine the impact of clustering traffic events based on a grid using native structures of a DB
- Waze-GC uses data structures that are already implemented in a RDB
 - Clustered B+ trees
 - **R-trees**
 - No additional structures

- Motivation: Clustering historic traffic events that occurred in a given area
 - Grid over the area of interest
- Possible to filter events using spatial information
- The grid-based strategy
 - Matrix of GCs of regular sizes associated
 - Set of values that represent geographical characteristics of the region

- An area of interest has a MBR
 - Upper left corner coordinate (latUL, longUL)
 - Lower right corner coordinate (latLR, longLR)
 - Bounding rectangle divided into GCs
 - Non-overlapping rectangles of the same size over the area of interest

- Limit of a GC -> Number rows (R) and columns (C)
- GC matrix -> GC Table
 - $\blacksquare R * C$ records

• This work considers linear representation of the matrix to obtain the GC's identifier (id_GC)

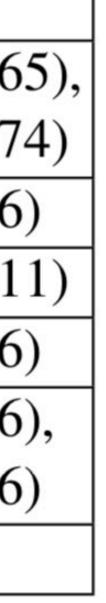
id_GC	geom
1	POLYGON(-49.3 -26.5, -49.2765 -26
2	POLYGON(-49.3 -26.47, -49.2765 -2
3	POLYGON(-49.3 -26.45, -49.2765 -2
	•••

6.5, -49.2765 - 26.475, -49.3 - 26.475, -49.3 - 26.5)26.475, -49.2765 -26.45, -49.3 -26.45, -49.3 -26.47) 26.45, -49.2765 -26.425, 49.3 -26.425, -49.3 -26.45)

- Tables clustered by the attribute id GC
- R-tree created on the geometry attribute

Waze-GC

II) street	pub_utc_date	id_GC	geometry
1	Florianópolis S.	2017-12-15 19:43:43	1	(x -48.833472, y -26.32846
				(x -48.837777, y -26.32987
2	Min. Calógeras S.	2017-12-14 17:35:39	1	(x -48.843751, y -26.30736
3	BR-101	2017-12-18 18:24:38	1	(x -48.870387, y -26.32041
4	Min. Calógeras S.	2017-12-14 17:35:39	1	(x -48.843751, y -26.30736
4	Min. Calógeras S.	2017-12-14 17:35:39	2	(x -49.387950, y -26.30736
				(x -49.389090, y -26.30736
	•••	•••		

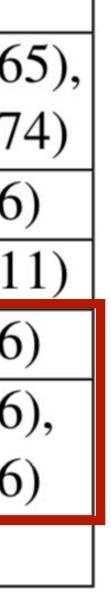


Primary key of the table is (event ID + id_GC)

Waze-GC

- Jams and irregularities have a list of points
- Record r contains points pl and p2 in different GCs it must be split

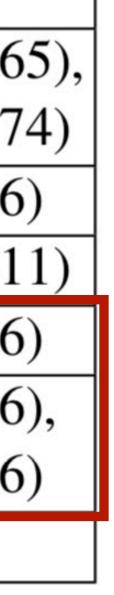
	ID	street	pub_utc_date	id_GC	geometry			
1	1	Florianópolis S.	2017-12-15 19:43:43	1	(x -48.833472, y -26.32846			
	1				(x -48.837777, y -26.32987			
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	+				(x -49.389090, y -26.30736			
		•••			•••			



- Two records created
- RI contains points up to pI and pint
- R2 contains pint and the rest
- Original event ID kept to identify points belong to same event from Waze

Waze-GC

	ID	street	pub_utc_date	id_GC	geometry		
1	1	Florianópolis S.	2017-12-15 19:43:43	1	(x -48.833472, y -26.32846		
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		•••					



- Advantage of the id_GC attribute
 - Filter records related to a set of GCs
 - Join query results from different type of events from same GC
- Jams and alerts may be combined if they occurred in the same GC

- Original Waze database
 - Postgres
 - Smart Mobility project.
 - The granting of data UDESC
 - I3 Gigabytes (GB)
 - September 2017 to September 2018



Clustered R-tree index was also defined on the geometry attribute of Waze

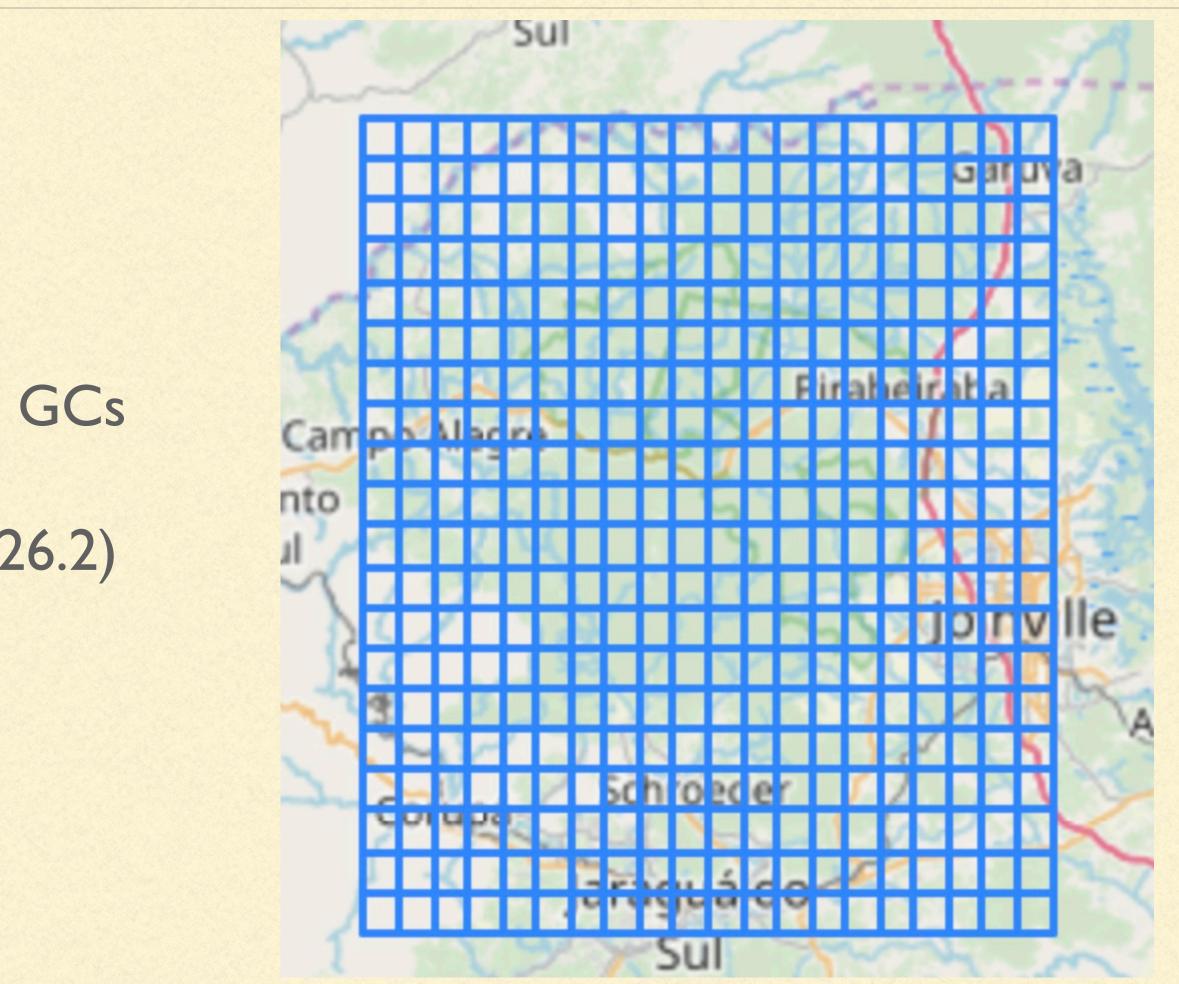
Database -> Waze

Waze-GC -> database generated by proposed approach



- Area of interest: City of Joinville
- Grid size to 20 lines and 20 rows = 400 GCs
- Delimited by (-48.72, -26.39) (-48.92, -26.2)
- Total area has 625 km
- Cells of 1.56 km



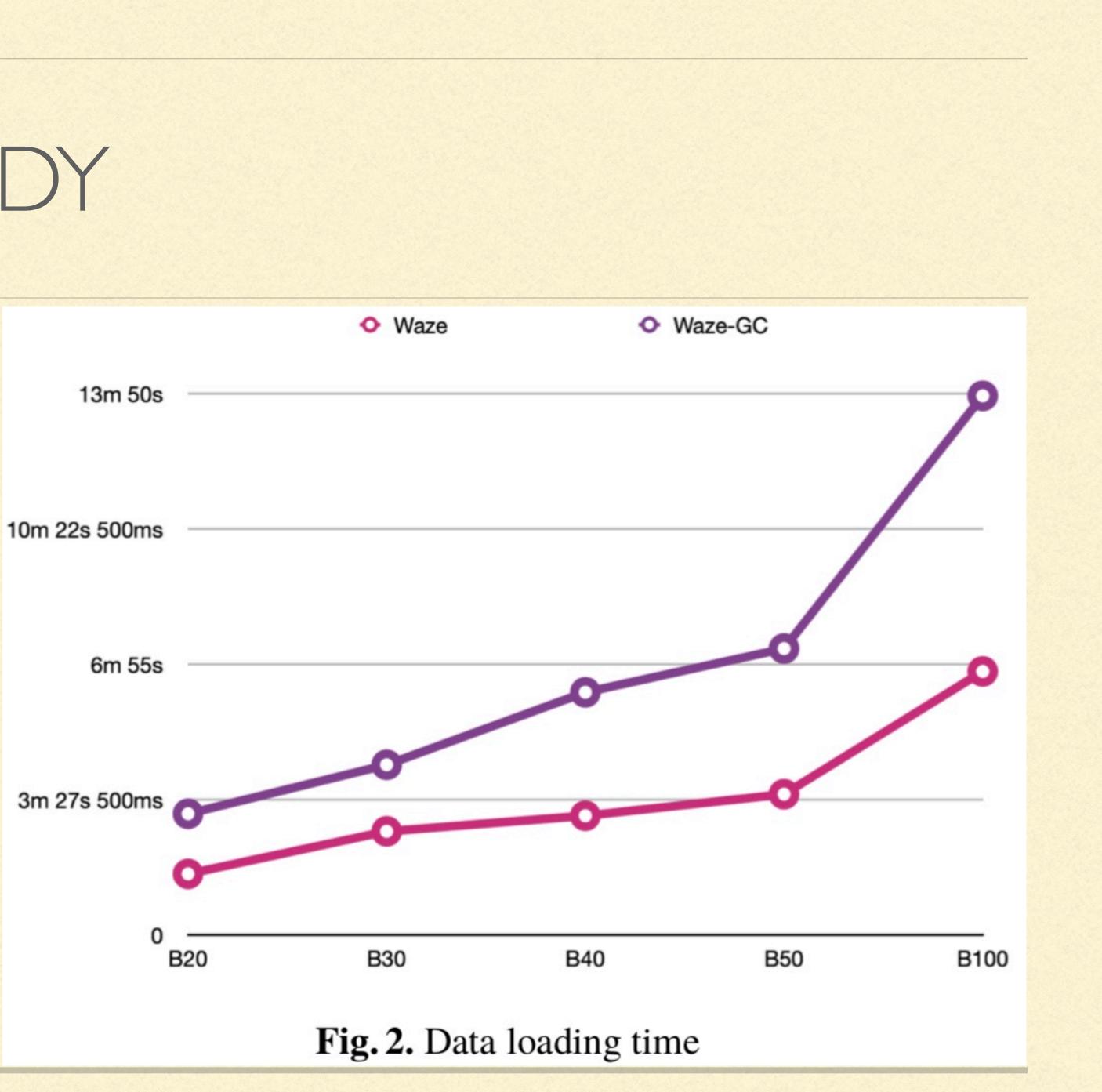


- Datasets created incrementally
- Starting with events in the central region of the city
- Larger number of records of jams and irregularities
- Set of points which may be split into different GCs

Databasa	Percentage	#Alerts	Waze		Waze-GC		
Database			# Jams	# Irregularities	# Jams	# Irregularities	#GCs
B20	20%	1024311	587816	22063	588616	22464	81
B30	30%	1536466	887724	33095	888928	33696	120
B40	40%	2048622	1183632	44126	1185230	44926	161
B50	50%	2560777	1479540	55158	1481544	65159	198
B100	100%	5121554	2959080	110316	2963087	112321	400



- Waze-GC time
 - Insertions on DB
 - Stored procedure for GCs
 - Splits list of points when needed
- Process doubles the load time



- Machine running Mac OS 10.15.2
- Dual-Core Intel Core m3 with 1.1 GHz
- 8 GB of main memory
- Two queries
 - Executed five times
 - Values consist of their average



- First query
 - Analyze impact of clustering events by id GC in Waze-GC
- street in the first seven days of 2018?"
- Waze and Waze-GC use spatial function ST Intersects from PostGIS



"Which streets had traffic jam and alert events that occurred at exactly the same point on a

R-Tree index defined on attribute geometry -> Enhance performance of ST Intersects



- Waze-GC over preforms Waze
- Advantage by the clustering on id_GC
 - Selectivity of the join condition
 - R-tree index clustering in Waze was less effective than in Waze-GC
 - Waze-GC only compares records in the same GC

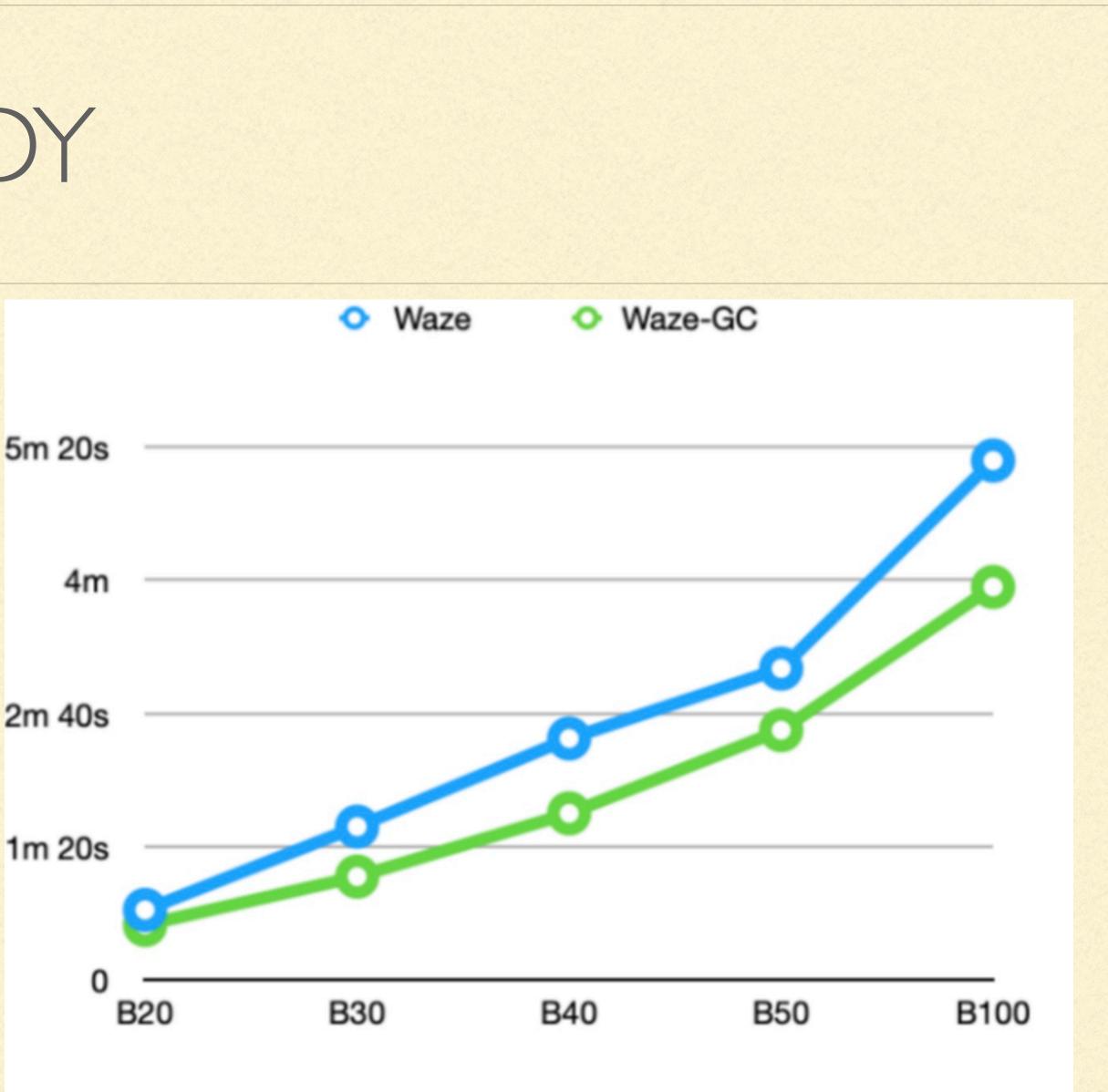
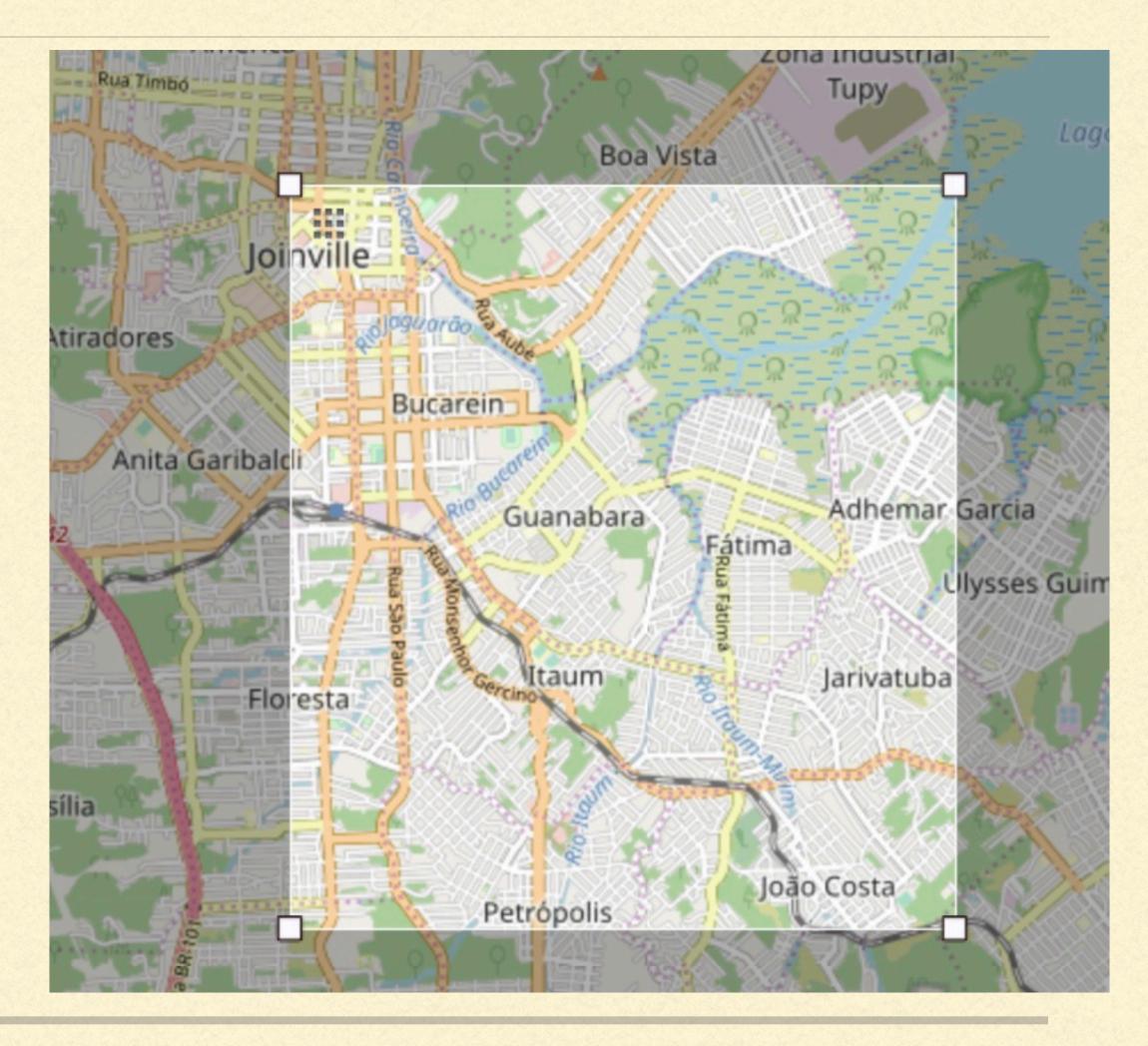


Fig. 3. Query 1 - Response Time

- Second query
 - Impact of using the GC table
 - id_GC index by Waze-GC
 - "Number of traffic jams in October 2017 in an informed area of interest"
 - The size of the area of interest is 6,25 km2







Waze-GC statement

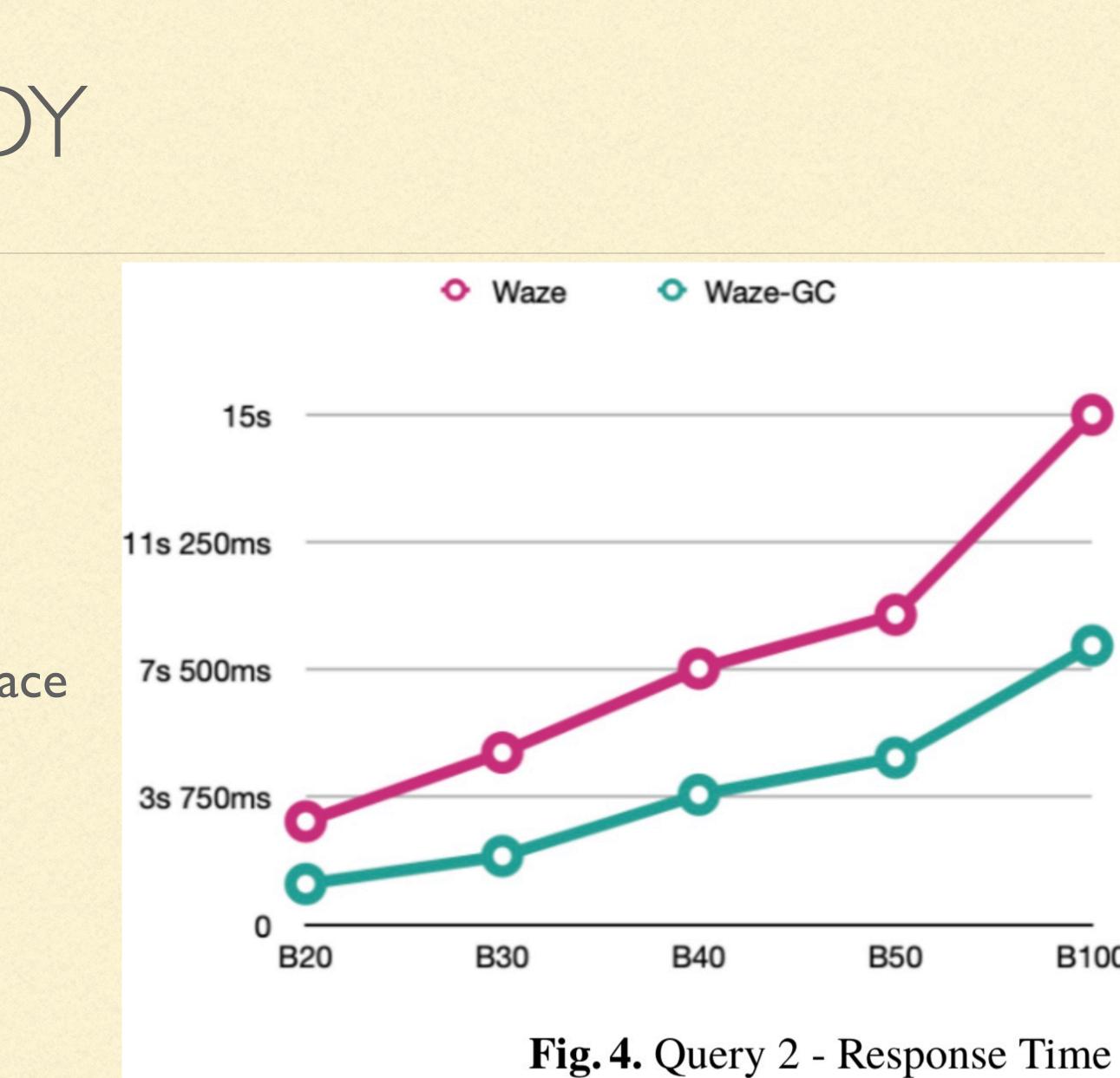
- Sub-query identifies GCs in GC Table that intersect area of interest
- Returns 4 GCs for all percentages



Advantage of Waze-GC

Filter id_GC -> Reduces the search space

GC Table -> Statement more complex





Approach for partitioning an area of interest -> a grid of juxtaposed GCs
Events that occurred in the same GC -> stored in a grouped manner
optimize their recovery
Use of an off-the-shelf relational database and index structure

- Study case -> traffic events from Waze
- Two forms of data storage were tested:
 - Waze relational database -> clustered R-tree index on the geometry
 - Waze with the additional GC attribute -> clustered by GC (Waze-GC)

- Test on data sets of increasing sizes: 20%, 30%, 40%, 50% and 100%
- Advantage in query processing time of Waze-GC -> compared to Waze
- Filter on GCs reduces the search space •
- More effective than an R-tree based clustering
- Query processing time is more expressive as the database size increases

- Waze-GC adds extra time on database load -> set the GC for each event
- Advantage of Waze-GC in query processing overcomes the shortcomings of its implementation costs

• Waze-GC has query statements more complex than usual -> GCs must be filtered

FUTURE WORK

- Determine the effect of the cell size -> better profile this approach
- Investigate its scalability
 - longer periods of time
 - larger geographic areas

- A comprehensive comparison between alternative methods is required

 Storage alternatives to reduce the clustering overhead for inserting new records Files -> possible to group traffic events based on their spatial-temporal proximity

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Thank you! GRID-BASED CLUSTERING OF WAZE DATA ON A RELATIONAL DATABASE

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